# **HC-RCM Stackable single axis levers remote control**



### **Technical specifications**

Working section number: 1 - 12

Max pressure: 60 bar

Oil capacity: 12 l/min

Weight HC-RCM/1: 1,5 Kg

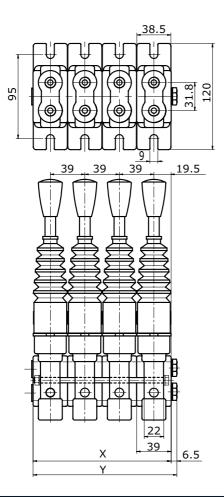
Tie rod clamping torque: **14 Nm** 

# **Applications**

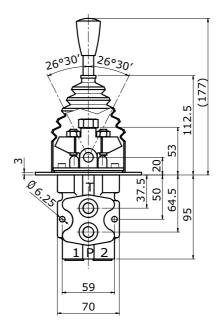
Mini steer loaders, Backhoe loaders, Tractors

Hydraulic remote control HC-RCM belongs to the wide range of Hydrocontrol products. Low operating efforts, low energy consumption and low maintenance make these hydraulic remote controls HC-RCM ideal for piloting remote control directional valves, variable displacement pumps and motors, auxiliary valves, frictions and hydraulic brakes. Each hydraulic remote control is assembled with N.2 tie rod kits which include a tie rod, two nuts and two washers. It can be assemble up to 12 working sections.

# **Dimensions**



# HYDRAULIC SCHEMA P T T 1 2 1 2 1 2 1 2 1 2



TYPE	/1	/2	/3	/4	/5	/6	/7	/8	/9	/10	/11	/12
X (mm)	39	78	117	156	195	234	273	312	351	390	429	468
Y (mm)	45,5	84,4	123,5	162,5	201,5	240,5	279,5	318,5	357,5	396,5	435,5	474,5
Weights (kg)	1,5	3	4,5	6	7,5	9	10,5	12	13,5	15	16,5	18

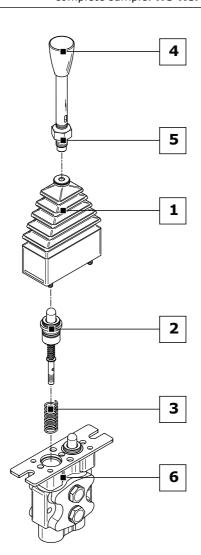




# **HC-RCM** order example

				HC-RCM/1:	01 - A01	- MA - N	1 - WE	95 - RA	G02
		product type working secti	on number						
1)		ROL CLASSIF 01	control type						
2)	METER 2.1	RING CURVE A01	curve type						
3)	RETUR	RN SPRING: MA	return spring type						
4)	HAND 4.1	LE CLASSIFI M	CATION: — handle type						
5)	5.1	R ROD CLASS WE 95	IFICATION: — lever rod type lever rod length						
5)	6.1	ARRANGEMI RA G02	ENT: ————————————————————————————————————						]

Ordering row 2 and 3, must be repeated for each port complete sample: HC-RCM/1 01 A01 MA A01 MA A01 M WE95 RA G02



### 1) CONTROL CLASSIFICATION: (pag. 26)

- 01 Return spring in neutral
- 02 Stroke end mechanical detent in position 1 and 2
- 03 Stroke end mechanical detent in position 1
- Stroke end mechanical detent in position 2

### 2) METERING CURVE: (pag. 72)

- **A**01 Linear metering curve with step
- **B**01 Linear metering curve without step
- **C**01 Broken line metering curve with step
- **D**01 Broken line metering curve without step

### 3) RETURN SPRING: (pag. 79)

MA	Preload 25 N	End stroke load 48 N
MB	Preload 14 N	End stroke load 27 N
MC	Preload 73 N	End stroke load 135 N
MD	Preload 89 N	End stroke load 169 N

# 4) HANDLE CLASSIFICATION: (pag. 80)

- Α Without micro-switch
- В With micro-switch to close
- С With micro-switch to close with detent
- D With dual micro-switch
- Impugnatura standard

### 5) LEVER ROD CLASSIFICATION: (pag. 28)

Levers depends on the handle and on the required control:

WE95 Leva standard per impugnatura M (95 mm) WE165 Leva standard per impugnatura M (165 mm)

# 6) BODY ARRANGEMENT: (pag. 29)

**RA G02** Standard Body (G 1/4 ports)

**RA U02** Standard Body (9/16"-18 UNF ports)

# **Control kit classification**

All controls installed on the remote control HC-RCM are interchangeable. Lever rod type must be choosen according to different control kit (see quick reference guide pag. 29). The controls shown correspond to standard configurations; for different applications contact our Commercial Dept.

CODE	CONFIGURATION	SCHEMA	DESCRIPTION
01		P T	Return spring in neutral
02		P T 2	Stroke end mechanical detent in position 1 and 2
03		P T	Stroke end mechanical detent in position 1
04		P T	Stroke end mechanical detent in position 2
19		P T  1 0 2	Return spring in neutral with micro-switch open in central position
31		P T  1 0 2	Return spring in neutral with micro-switch closed in central position



CODE	CONFIGURATION	SCHEMA	DESCRIPTION
25		P T	Security handle in neutral
17		1 0 2	Security handle in neutral with micro-switch closed in central position
12			Security handle in neutral with micro-switch open in central position
26		P T	Friction
18		P T  1 0 2	Friction with micro-switch closed in central position
13		P T  1 0 2	Friction with micro-switch open in central position
27		P T 1 2	Friction and security handle in neutral

### **Microswitches specifications**

Direct current load resistive: **5 A / 30 Vdc**Direct current load inductive: **3 A / 250 Vac**Alternative current load resistive: **5 A / 30 Vdc**Alternative current load inductive: **2 A / 250 Vac** 

### **Lever rod classification**

The lever rod kits applied to all the HC-RCM hydraulic remote controls designed by Hydrocontrol change according to the type of control used and, above all, the type of handle. For improved clarity, all the possible lever rod configurations divided according to handle are listed here below. Straight and curved lever rods are available in several lengths and dimensions.

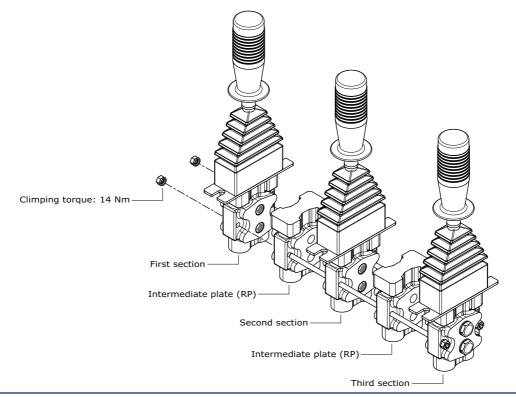
	IDENTIFICATION ROD LEVER HANDLE "A-B-C-D" - QUICK REFERENCE GUIDE														
6	ode	Dimensional	nensional Control type												
	oue	drawing	01	02	03	04	12	13	17	18	19	25	26	27	31
WA70			•	•	•	•		•		•	•				•
WQ70 (only for "A" handle)		012 M12											•		

Handles type "A-B-C-D" are only available with HC-RCM/1. To set up an HC-RCM remote control with any number of sections between 2 and 12, an intermediate plate must be used identified by the order code RP.

### Order example RCM/3 with "RP" intermediate plate

HC-RCM/3: <u>01-A01-MA-A WA70-RA G02</u> - **RP** - <u>01-A01-MA-A WA70-RA G02</u> - **RP** - <u>01-A01-MA-A WA70-RA G02</u>

,	FIRST SECTION:  INTERMEDIATE PLATE:		
3)	SECOND SECTION:		
4)	INTERMEDIATE PLATE:		
5)	THIRD SECTION:		







	IDENTI	FICATION ROD LEVER H	AND	LE "I	М" -	QUI	CK R	EFER	RENC	E GL	JIDE				
Co	de	Dimensional	Control type												
		drawing	01	02	03	04	12	13	17	18	19	25	26	27	31
WE95		95	•	•	•	•		•		•	•				•
WE165		165	•	•	•	•		•		•	•				•
WM95		95 95 WIT					•		•						
WM165		165 Z W					•		•						
WN95		95										•		•	
WR95		95 W 27 W 2											•		

# **Body arrangement**

 $The \ hydraulic \ remote \ control\ HC-RCM\ has\ only\ one\ setting\ body,\ the\ only\ variable\ is\ represented\ by\ a\ different\ thread$ 

CODE	CONFIGURATION	SCHEMA	DESCRIPTION
RA G02		P T	Standard body with ports G 1/4
RA U02	Tank port (T) Inlet port (P) Port (1)	1 2	Standard body with ports 9/16" - 18 UNF